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9. PERMANENT MAGNET SYNCHRONOUS MACHINE (PMSM) 1

Figure 9.1 A Low-inductance Rotor Configuration Of A Permanent Magnet Synchronous Machine. The Left-hand Depiction Illustrates A Non-salient Pole Structure. In The Right-hand Structure, The Steel Rim Is Made As Thin As Possible On The D-axes To Reduce The Inertia Of The Machine. The Flux Diagram Of The D-axis Shows That There Is A Suitable Path ... 1th, 2024

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Into Current Model-based And Extended Electromotive Force (EMF)-based Methods [2,3]. Currently, The Latter Method Is Commonly Used Because Of Its Fast-tracking Capability Using The Arc-tangent Calculation. To Estimate The Rotor Position, The Model-based Sensorless Control Method Utilizes 1th, 2024

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2.2 Ultra Sparse Matrix Converter Ultra Sparse Matrix Converter (USMC) Is The Simplest Variant Of Sparse Matrix Converter Developed From Indirect Matrix Converter In [9]. This Converter Consists Of The Rectifier Stage With 3 Unidirectional Active Switches And The Inverter Stage Wi 2th, 2024

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• Method B: A Voltage Probe And Driving Motor, Which Spins The Motor Guide For Method A: The Following Steps Describe The Method To Determine The High Number Of Motor Pole Pairs. 1. Spin The Motor By An Inverter Using Volt/Herz

Method And Set The Frequency In Such A Way That The Motor 3th, 2024

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The Dual Motor Control Requires Running Two Motor Control Algorithms In Parallel. Figure 3 Shows The Field-oriented Control (FOC) Principle Of A PMSM. The Key To FOC Is To Control The Motor Torque And Field Excitation, Or, The Motor Magnetic Flux, Independently And Separately. The Operating Principles Of The Two Control Loops Are Discussed Below: 2th, 2024

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