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### DESIGN, ANALYSIS And FABRICATION OF A RECONFIGURABLE STAIR ...

3 Department Of Mechanical Engineering National Institute Of Technology Rourkela- 769008 Odisha, India Www.nitrkl.ac.in CERTIFICATE This Is To Certify That The Thesis Entitled "Design, Analysis And Fabrication Of A Reconfigurable Stair Climbing Robot" Submitted By Ashish Singh (Roll No. 710ME4089) To National Institute Of Technology Rourkela, Is A Record Of Bonafide Research Work Under My ... 1th, 2024

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Of Columbus® Total Knee Prostheses (B. Braun Aesculap, Tuttlingen, Germany) With Different Platform Designs, Degrees Of Congruency And PCL Management Are Compared. Variations Of The Columbus Knee Have Been Previously Investigated, Either Between Different Bearing Designs 2th, 2024

## Design And Implementation Of Stair-Climbing Robot For ...

Power Sources, Charger Circuit, Motors (DC Motor, Servo Motor, Stepper Motor), And Wireless And Wire Modules. The Brain Of The Robot Is PIC16F877A. The Following Sections Describe In Details Each Of These Components. Figure (4) Block Diagram Of The Stair-Climbing Robot . Power Sources . Primary Source Of Power For The Robot Are Lithium 1th, 2024

#### **Rubber Stair Treads, Risers & Stringers**

INSTALLATION INSTRUCTIONS And TECHNICAL DATA Distinct Designs RUBBER STAIR TREADS, RISERS & STRINGERS TECHNICAL DATA ASTM F2169 – Resilient Stair Treads: Type TS, Class 1 & 2, Group 1 & 2, Grade 1 ASTM E648 (NFPA 253) -Critical Radiant Flux: Class I, > 0.45 W/cm2 ASTM E662 (NFPA 258) - Smoke Density: Passes,