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PID Controllers: An Overview (Continue) Classical PID Controller Design The Ziegler-Nichols Step Response Method
 $C(s) = k_P + K_I S + k_D s$
 $K_D s + 1 + T_D s$
For A Small T_D The Method Is An Experimental Open-loop Tuning
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state Error; However, As Seen Below, They Also Lead To A Faster, Less Damped Response Apr 3th, 2024.

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