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Synchronous Motors□Hiroyuki Kaimori Et Al.□  $V_D V_Q$   
 $= R_A I_D I_Q + \psi M \dots$  (1) Where  $V_D, V_Q, I_D, I_Q, L_D, L_Q$  Are The D-  
and q-axis Voltages, Currents, Self-inductances,  
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RAE Motor: Is Designed For Applications Requiring High Output Torques And A Dependable, Rugged Design. Fe  
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