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Kinematics H.I. Robot Kinematics Intro Coords Henrik I ...Kinematics H.I. Christensen

Intro Coords Models Maneuverability Workspace Beyond Basics Control Wrapup
 Kinematic Modelling Goal: Determine The Robot Speed $\dot{\xi} = \begin{bmatrix} \dot{x} \\ \dot{y} \\ \dot{\theta} \end{bmatrix}^T$ As A
 Function Of Wheel Speed $\dot{\phi}$, Steering Angle β , Steering Speed $\dot{\beta}$ And The
 Geometric Parameters Of The Robot. Forwar 7th, 2024Name Perio Kinematics-
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