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Topic #14 16.31 Feedback Control Full-state Feedback ...

X State Step Response X 1 X 2 0 0.5 1 1.5 2 2.5 3 3.5 4 -15 -10 -5 0 5 Time (sec) U Control Step Response: $U = Nbar R - Kx$ U = Nbar R - Kx Figure 3: Response To Step Input With The N^- Correction. Gives The Desired Steady- Apr 3th, 2024

Dynamic Programming Techniques For Feedback Control

One Of The Main Appeals Of The Dynamic Programming Approach Resides In The Fact That The Optimal Control Can Be Determined In State Feedback Form $F(x) = A*(0)$ For A Horizon Δ That Can Be Made As Small As Physically Meaningful (e.g., The Control Period For A Computer Controlled Mar 1th, 2024

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