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In Figure 1, a Schematic [1] Of A Five-finger Hand Moved By A Single Actuator Is Shown; The Auto-adaptability Of The Fingers To The Shape Of The Grasped Object Is Obtained By Means Of “sliding Pulleys”. In Figure 1b A Study [2] Is Presented, In Cesare Rossi And Sergio Savino: An Underactuated Multi-finger Grasping Device 1 ARTICLE Feb 14th, 2024
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