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14. Speed Changer Type Inverter 15. Clutch & Brake Spring Return Type / Air Clutch 16. Lubrication Centralized Oil Lubrication 17. Working Air Pressure Kg/cm² 5 - 7 18. Hopper Capacity (approx.) Liter 15 18 18 60 60 19. Reducer Type Cyclo Reducer 20. Net Weight (approx.) Kg 2,500 3,500 4,000 6,000 Feb 19th, 2024

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Introduction To The Mobile Robotics Lab (OTA Lab) 2021

Keywords: Mobile Robot, Simple Contact Model, Manipulation Planning, Modal Planning Releece: [1] S. Shirafuji, Et Al. Mechanism Allowing Large-force Application By A Mobile Robot, And Development Of ARODA. Robotics An Apr 9th, 2024

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